

B6.0 A DIRECT EXPRESSION FOR LINES OF CONSTANT VIEW TIME AS A FUNCTION OF RELATIVE INCLINATION AND PHASE

$$\frac{D^2}{2R^2} = 1 - \cos(\theta + \phi)\cos\theta - \sin(\theta + \phi)\sin\theta\cos\theta$$

is the initial expression for range given the T (time of viewing) should be a function symmetric about  $\theta = -\phi/2$ 

let

$$\theta = -\frac{\phi}{2} + \omega t$$

then

$$\frac{D^{2}}{2R^{2}} = 1 - \cos\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} - \omega t_{i}\right) + \sin\left(\frac{\theta}{2} + \omega t_{i}\right) \sin\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} + \omega t_{i}\right) \sin\left(\frac{\theta}{2} + \omega t_{i}\right) \cos\left(\frac{\theta}{2} + \omega t_{$$

where

This function is symmetric in + and - t,

Setting a camera range: D = CR

and setting a time  $t_1$ :  $t_1 = \underline{T}_2$ 

gives a parametric equation between  $\phi$  and i.